# 1991: The Steiner Tree Problem

The cost for a communication line between two stations is proportional to the length of the line. The cost for conventional minimal spanning trees of a set of stations can often be cut by introducing "phantom" stations and then constructing a new *Steiner tree*. This device allows costs to be cut by up to 13.4% $(= 1 - \sqrt{3}/2)$. Moreover, a network with n stations never requires more than $n - 2$ points to construct the cheapest Steiner tree. Two simple cases are shown in **Figure 1**.
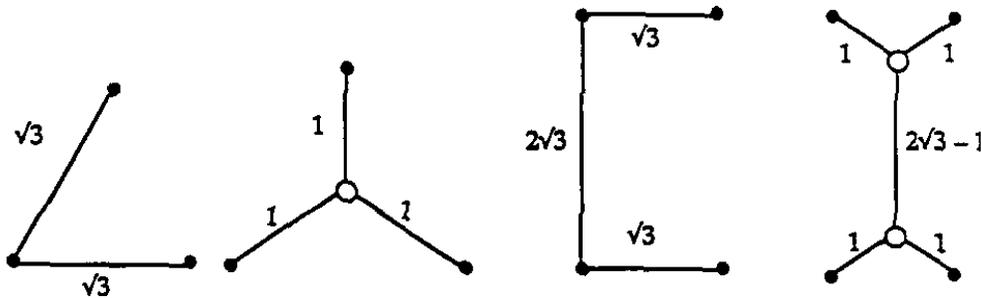
Figure 1. Two simple cases of forming the shortest Steiner tree for a network.

For local networks, it often is necessary to use rectilinear or "checkerboard" distances, instead of straight Euclidean lines. Distances in this metric are computed as shown in **Figure 2**.
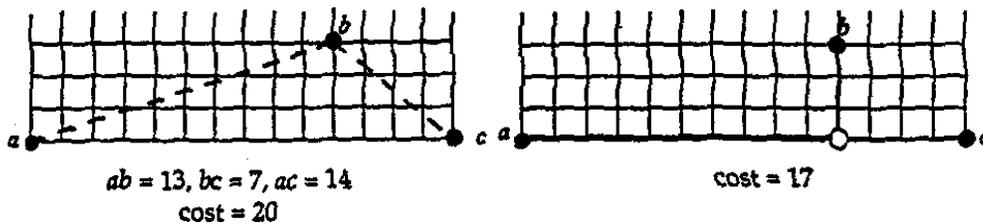
Figure 2. Comparison of distances using straight Euclidean line distances ($ab = 13$, $bc = 7$, $ac = 14$; cost = 20) vs. using rectilinear distances (cost = 17).

Suppose you wish to design a minimum cost spanning tree for a local network with 9 stations. Their rectangular coordinates are:

$$a(0, 15), \quad b(5, 20), \quad c(16, 24), \quad d(20, 20), \quad e(33, 25),$$

$$f(23, 11), \quad g(35, 7), \quad h(25, 0), \quad i(10, 3).$$

You are restricted to using rectilinear lines. Moreover, all "phantom" stations must be located at lattice points (i.e., the coordinates must be integers). The cost for each line is its length.

1. Find a minimal cost tree for the network.

2. Suppose each station has a cost $d^{3/2}w$, where d = degree of the station. If $w = 1.2$, find a minimal cost tree.

3. Try to generalize this problem.

Comments by the Contest Director

I (Ben Fusaro) contributed this problem; I got the idea from an article by Barry Cipra [1991].

Reference

Cipra, Barry A. 1991. Euclidean geometry alive and well in the computer age. *SIAM News* 24(1) (January 1991): 1, 16–17, 19.